

Measuring Robustness of Deep Learning Model for Head and Neck Tumor Volume Delineation

Chloe Griffin | August 2nd, 2023

Overview

1. Project Goals

- Tumor Volume Delineation
- Measuring Robustness

2. Monai Tutorial

- General Use
- Transformations

3. Next Steps

- Defining Robustness
- Proposed Inference Protocol
- Open Questions

Project Goals
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Monai Tutorial
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Next Steps
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Summer Project

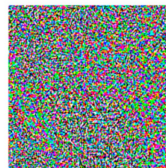
- Visiting from Brown University
- Two and a half month stay
- Advised by Alexandra Walter
- Work with trained nnU-Net model
 - Deep-learning biomedical segmentation method
 - Self-configuration
 - Trained for head and neck tumor volume delineation
- Measure neural network robustness (funny on right) [1]
- Develop procedure and analyze results



“panda”

57.7% confidence

+ .007 ×



noise

=



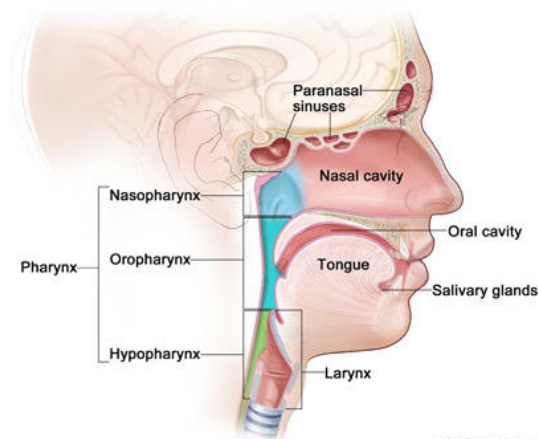
“gibbon”

99.3% confidence

Tumor Volume Delineation

- Vital for head and neck cancer (HNC) radiotherapy
- Includes several sensitive regions (right) and near organs at risk [2]
- 800,000 new cases of HNC globally each year [3]
- Ionizing radiation damages DNA and destroys malignant cells
- Life-threatening postradiation changes [4]

Head and Neck Cancer Regions



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Automating the Process

- Computer tomography (CT) scans determine tissue density and gross tumor volumes [5]
- Oncologists segment scans by hand
- Average of three hours per patient
- Results are highly subjective
- Vary from expert to expert
- Single clinician results not always consistent [6]

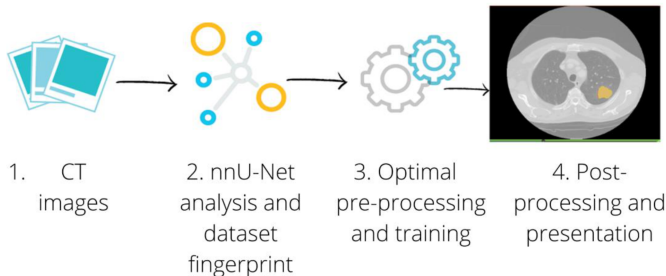


Figure: Example of automated tumor delineation pipeline [7]

Clinical Target Volume Delineation

- Gross Target Volume (GTV): Initial tumour volume
- Clinical Target Volume (CTV): GTV + volume with high probability of microscopic disease

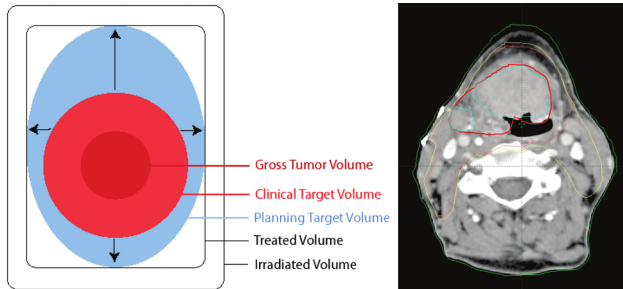


Figure: Schematic diagram of CTV (on left) and labeled slice with GTV in red and CTV in yellow (on right) [8]

- “No new net:”
 - Primary advancement: automatically configures many aspects of the training process
 - Includes preprocessing, post-processing, and architecture structure
 - Methods and details can be found in [9]
- General segmentation tool
 - Divide an image key segments or isolate objects of interest
 - 2020, outperform other models due to automatic configuration
 - Task specific training may improve performance
 - Trained with Dice coefficient [9]

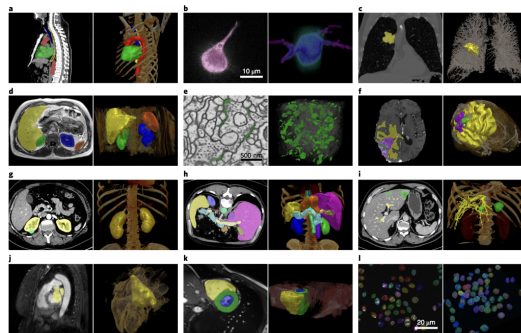


Figure: Examples of nnU-net applications

Data and Training

- Training and testing data was obtained from four cohorts
- 104 patient CT data sets for the model
- Split into 86 for training and 18 for testing
- Trained with original CT scan and manual CTV labels
- Scans were manually delineated at the German Cancer Research Center (DKFZ)

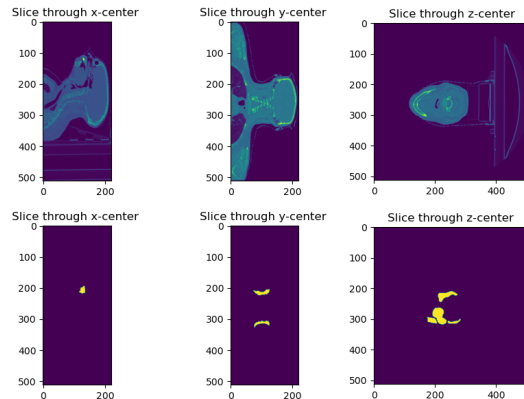


Figure: Example slices from CT scans and manual labels

Dice and sDice Metrics

■ Dice:

- Measures volumetric overlap
- Ranges from 0 to 1
- Insensitive to small deviations with large structures
- Sensitive to image processing changes with small structures

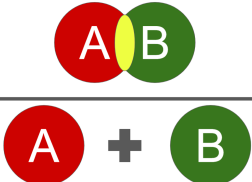
$$2 \times \frac{\text{A} \cap \text{B}}{\text{A} \cup \text{B}}$$


Figure: Formula for computing Dice metric [10]

■ sDice:

- Measures surface overlap
- Ranges from 0 to 1
- Penalizes border placement outside tolerance
- Clinically significant for small deviations [4]

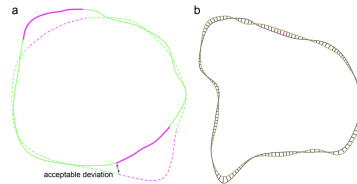


Figure: (a) Visual representation of sDice (b) Obtaining tolerance from oncologist manual labels [4]

Measuring Robustness

Goal: Measure how output metrics change given input perturbations

General Approach:

- 1 Systematically rotate CT scans and labels by varying degrees
- 2 Feed rotated CT scan into the trained nn-Unet model
- 3 Compare prediction metrics after rotation with prediction metrics prior to rotation
- 4 Obtain measure of robustness using existing standards

Built Python pipeline:

- 1 Rotates CT scans and labels by desired degree,
- 2 Feeds rotated CT scan into the trained nn-Unet model,
- 3 Scores prediction with Dice and sDice metrics

To-do:

- 1 Determine best approach for sampling rotations
- 2 Decide on most relevant standard for robustness

Introducing Monai

- "Medical Open Network for AI"
- Pytorch-based
- Open-source
- Deep learning Framework
- Emphasis on healthcare imaging
- Pytorch Ecosystem
- Started by NVIDIA and King's College London
- 167 contributors [11]

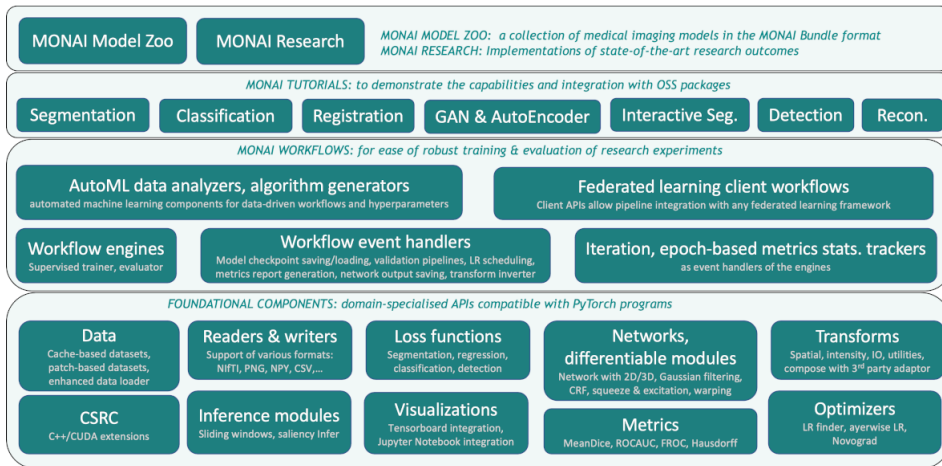


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Next Steps
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Monai Applications and Use Cases

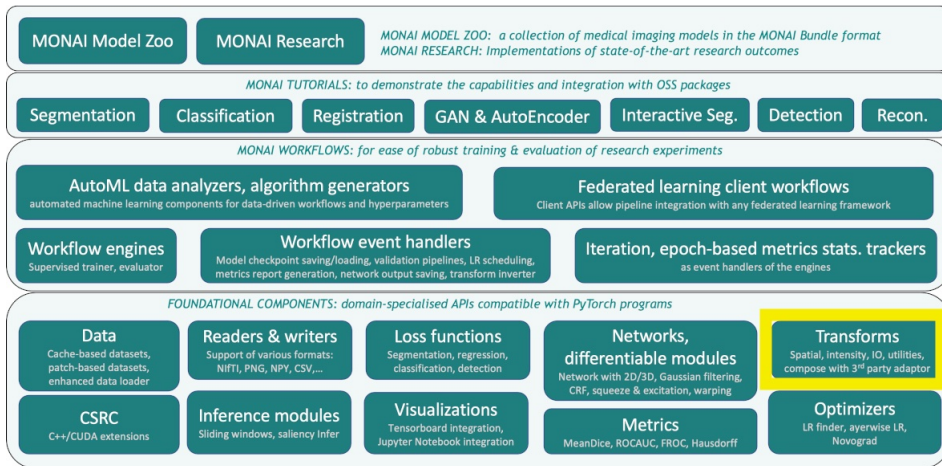


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Next Steps
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Monai Applications and Use Cases



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Monai Transformations

- Many transformations found in [Monai documentation](#)
- Dictionary transformations
 - Create list of dictionaries with associated paths to stored image and label data
 - Use [Compose](#) function to load, transform, and save images
 - Create [Monai dataset](#) as input of PyTorch DataLoader and continue with training, inference, etc.

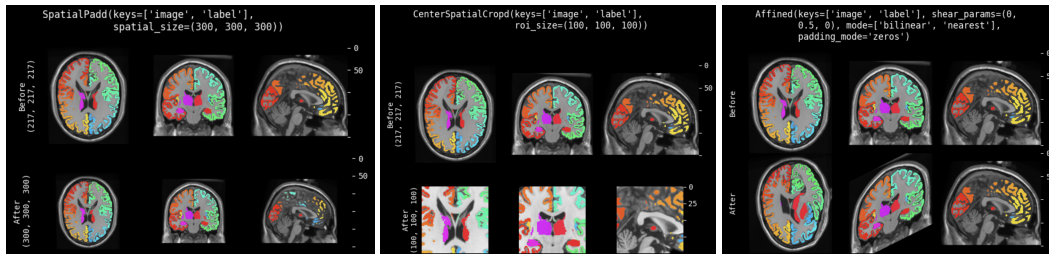


Figure: Examples of Monai Dictionary Transformations

Rotating 3D Images with Monai

- 1 Load image and label
- 2 Ensure Channel First
- 3 Use BorderPad to ensure correct fill values for rotation
- 4 Affined rotation, padded with maximal spatial size for any rotation
- 5 Save image

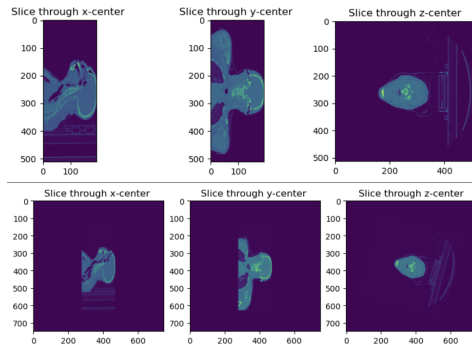


Figure: Example image before and after rotation with 15 degree rotation about z-axis

Defining Robustness

“Robustness measures the resilience of a system towards perturbations in any of its components”[12]

■ Local Robustness

- For a given input x , model provides same result for x and all inputs x' within ball of radius δ centered at x

■ Global Robustness

- Model is locally robust for all inputs in the input space [13]

■ Adversarial Robustness

- Worst-case scenario, model's ability to resist being fooled

■ Probabalistic/Physically Real Robustness

- Probability that difference in δ close inputs satisfy Lipschitz property is greater than $(1 - \epsilon)$

$$\Pr_{x, x' \sim D} (||f(x') - f(x)|| \leq k * ||x' - x||) \mid ||x' - x|| \leq \delta) \geq 1 - \epsilon$$

- Still difficult to verify, but only have to show true with probability of at least $(1 - \epsilon)$ with respect to realistic input distribution

Proposed Inference Protocols

- Mean Absolute Error of Dice and sDice as robustness metric

$$DiceMAE(\epsilon) = \frac{\sum_{i=1}^n (|O_{Dice}^i - AR_{Dice}^i(\epsilon)|)}{n}$$

$$sDiceMAE(\epsilon) = \frac{\sum_{i=1}^n (|O_{sDice}^i - AR_{sDice}^i(\epsilon)|)}{n}$$

where n is number of patient samples, O_{Dice}^i is score of a given sample prior to rotation, AR^i is score of the given sample after rotation, and $\epsilon = \begin{bmatrix} a & b & c \end{bmatrix}$ is the rotation array about (x, y, z)

- Plot with respect to increasing rotation around each axis
- Use Wilcoxon signed-rank tests (non-parametric alternative to t-test) to see if selected perturbations lead to significantly different Dice scores across samples as in [14].

Open Questions

- 1 Should we focus on realistic cases for robustness test? Or take adversarial approach?
- 2 Is there an exact criterion to answer “is this neural network robust”? Is this too problem dependent?
- 3 If adversarial, should we stick with rotations across one axis at a time? Or try rotating across several dimensions at once since we have the capacity?




Questions?

Project Goals
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