

Measuring Robustness of Deep Learning Model for Head and Neck Tumor Volume Delineation

Chloe Griffin | August 2nd, 2023

Overview

1. Project Goals

- Tumor Volume Delineation
- Measuring Robustness

2. Monai Tutorial

- General Use
- Transformations

3. Next Steps

- Defining Robustness
- Proposed Inference Protocol
- Open Questions

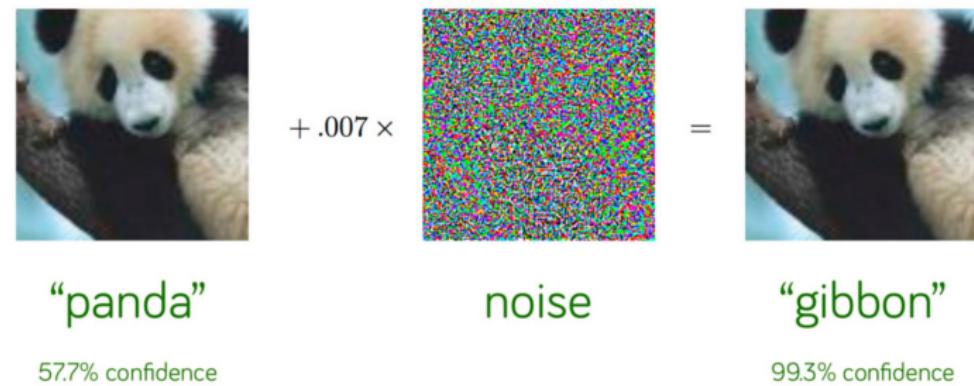
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Summer Project

- Visiting from Brown University
- Two and a half month stay
- Advised by Alexandra Walter
- Work with trained nnU-Net model
 - Deep-learning biomedical segmentation method
 - Self-configuration
 - Trained for head and neck tumor volume delineation
- Measure neural network robustness (funny on right) [1]
- Develop procedure and analyze results



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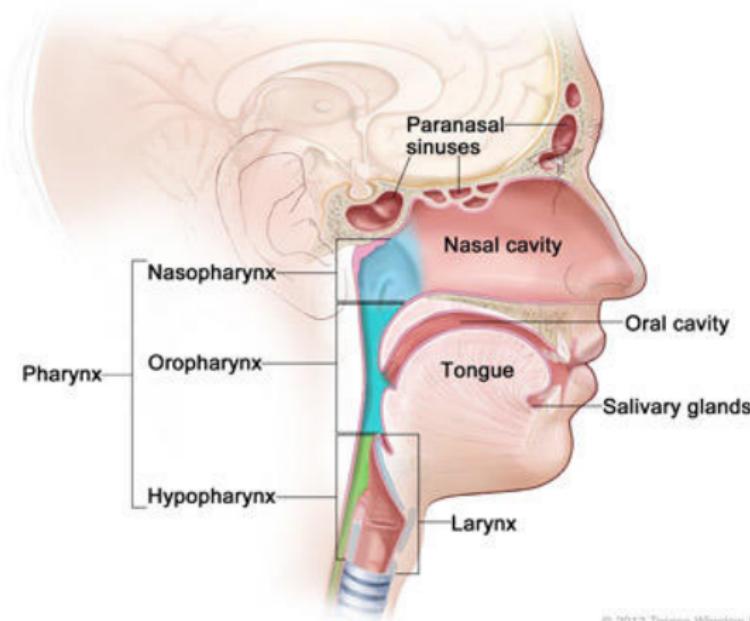
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Tumor Volume Delineation

- Vital for head and neck cancer (HNC) radiotherapy
- Includes several sensitive regions (right) and near organs at risk [2]
- 800,000 new cases of HNC globally each year [3]
- Ionizing radiation damages DNA and destroys malignant cells
- Life-threatening postradiation changes [4]

Head and Neck Cancer Regions



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Automating the Process

- Computer tomography (CT) scans determine tissue density and gross tumor volumes [5]
- Oncologists segment scans by hand
- Average of three hours per patient
- Results are highly subjective
- Vary from expert to expert
- Single clinician results not always consistent [6]

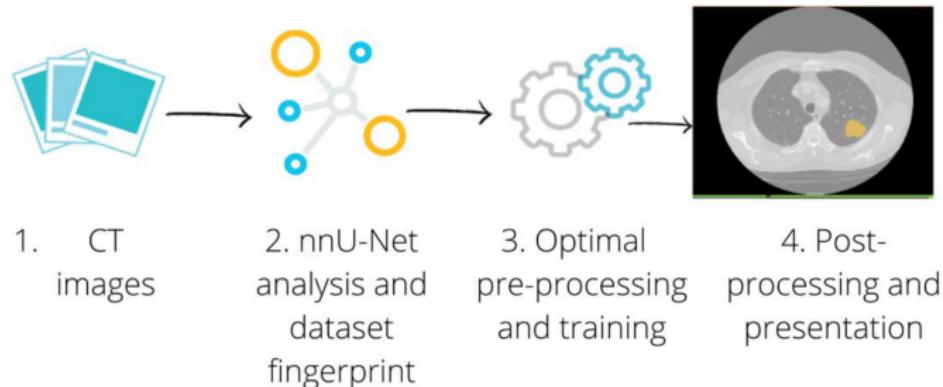


Figure: Example of automated tumor delineation pipeline [7]

Clinical Target Volume Delineation

- Gross Target Volume (GTV): Initial tumour volume
- Clinical Target Volume (CTV): GTV + volume with high probability of microscopic disease

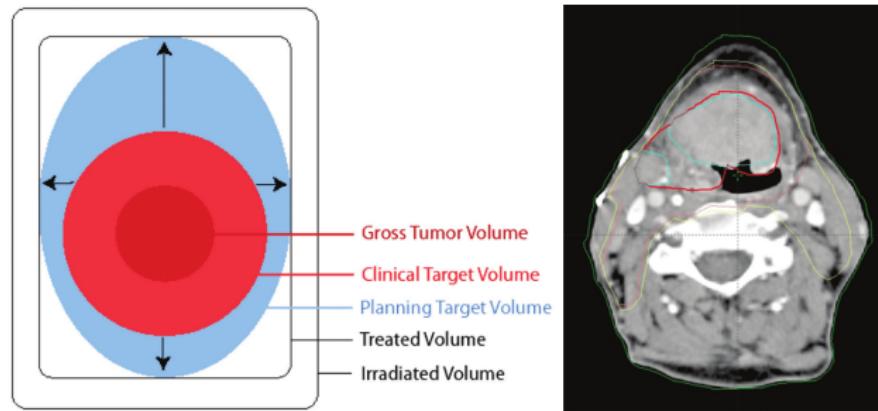


Figure: Schematic diagram of CTV (on left) and labeled slice with GTV in red and CTV in yellow (on right) [8]

nnU-Net

- “No new net:”
 - Primary advancement: automatically configures many aspects of the training process
 - Includes preprocessing, post-processing, and architecture structure
 - Methods and details can be found in [9]
- General segmentation tool
 - Divide an image key segments or isolate objects of interest
 - 2020, outperform other models due to automatic configuration
 - Task specific training may improve performance
 - Trained with Dice coefficient [9]

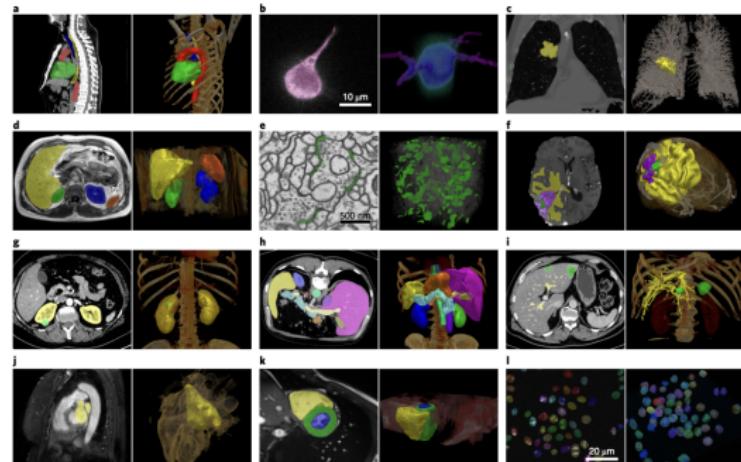


Figure: Examples of nnU-net applications

Data and Training

- Training and testing data was obtained from four cohorts
- 104 patient CT data sets for the model
- Split into 86 for training and 18 for testing
- Trained with original CT scan and manual CTV labels
- Scans were manually delineated at the German Cancer Research Center (DKFZ)

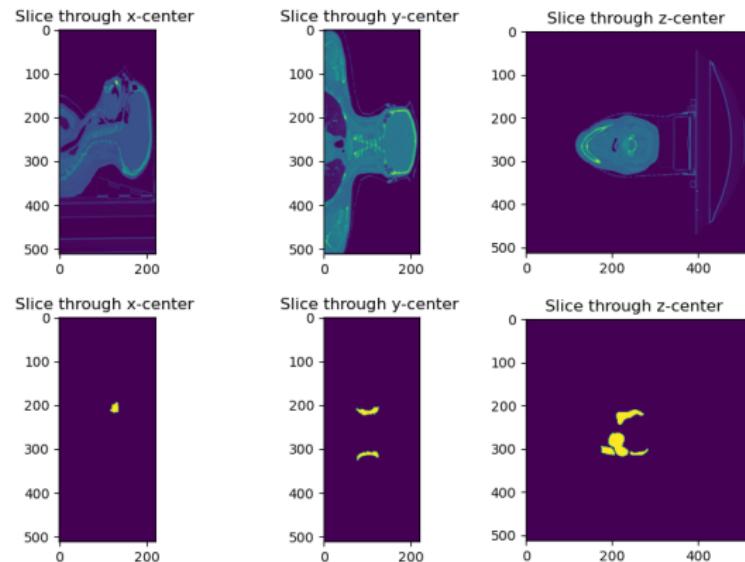


Figure: Example slices from CT scans and manual labels

Dice and sDice Metrics

- Dice:

- Measures volumetric overlap
- Ranges from 0 to 1
- Insensitive to small deviations with large structures
- Sensitive to image processing changes with small structures

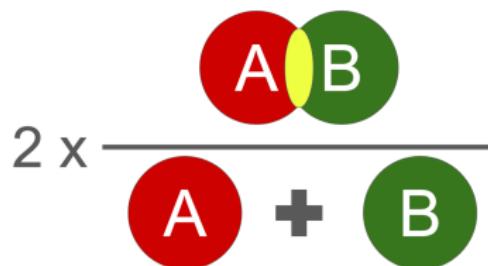


Figure: Formula for computing Dice metric [10]

- sDice:

- Measures surface overlap
- Ranges from 0 to 1
- Penalizes border placement outside tolerance
- Clinically significant for small deviations [4]

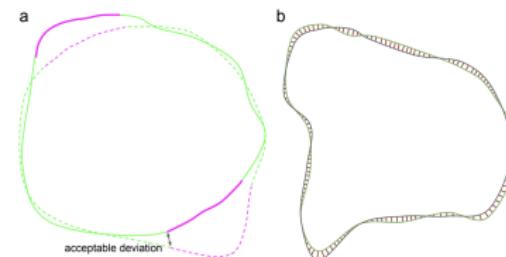


Figure: (a) Visual representation of sDice (b) Obtaining tolerance from oncologist manual labels [4]

Measuring Robustness

Goal: Measure how output metrics change given input perturbations

General Approach:

- ① Systematically rotate CT scans and labels by varying degrees
- ② Feed rotated CT scan into the trained nn-Unet model
- ③ Compare prediction metrics after rotation with prediction metrics prior to rotation
- ④ Obtain measure of robustness using existing standards

Built Python pipeline:

- ① Rotates CT scans and labels by desired degree,
- ② Feeds rotated CT scan into the trained nn-Unet model,
- ③ Scores prediction with Dice and sDice metrics

To-do:

- ① Determine best approach for sampling rotations
- ② Decide on most relevant standard for robustness

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Introducing Monai

- "Medical Open Network for AI"
- Pytorch-based
- Open-source
- Deep learning Framework
- Emphasis on healthcare imaging
- Pytorch Ecosystem
- Started by NVIDIA and King's College London
- 167 contributors [11]



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Monai Applications and Use Cases

MONAI Model Zoo

MONAI Research

MONAI MODEL ZOO: a collection of medical imaging models in the MONAI Bundle format
MONAI RESEARCH: Implementations of state-of-the-art research outcomes

Segmentation

Classification

Registration

GAN & AutoEncoder

Interactive Seg.

Detection

Recon.

MONAI TUTORIALS: to demonstrate the capabilities and integration with OSS packages

AutoML data analyzers, algorithm generators

automated machine learning components for data-driven workflows and hyperparameters

Federated learning client workflows

Client APIs allow pipeline integration with any federated learning framework

Workflow engines

Supervised trainer, evaluator

Workflow event handlers

Model checkpoint saving/loading, validation pipelines, LR scheduling, metrics report generation, network output saving, transform inverter

Iteration, epoch-based metrics stats. trackers

as event handlers of the engines

FOUNDATIONAL COMPONENTS: domain-specialised APIs compatible with PyTorch programs

Data

Cache-based datasets, patch-based datasets, enhanced data loader

Readers & writers

Support of various formats: NIFTI, PNG, NPY, CSV, ...

Loss functions

Segmentation, regression, classification, detection

Networks, differentiable modules

Network with 2D/3D, Gaussian filtering, CRF, squeeze & excitation, warping

Transforms

 Spatial, intensity, IO, utilities, compose with 3rd party adaptor

CSRC

C++/CUDA extensions

Inference modules

Sliding windows, saliency Infer

Visualizations

Tensorboard integration, Jupyter Notebook integration

Metrics

MeanDice, ROCAUC, FROC, Hausdorff

Optimizers

LR finder, aiyerwise LR, Novograd

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Monai Transformations

- Many transformations found in [Monai documentation](#)
- Dictionary transformations
 - Create list of dictionaries with associated paths to stored image and label data
 - Use [Compose](#) function to load, transform, and save images
 - Create [Monai dataset](#) as input of PyTorch DataLoader and continue with training, inference, etc.

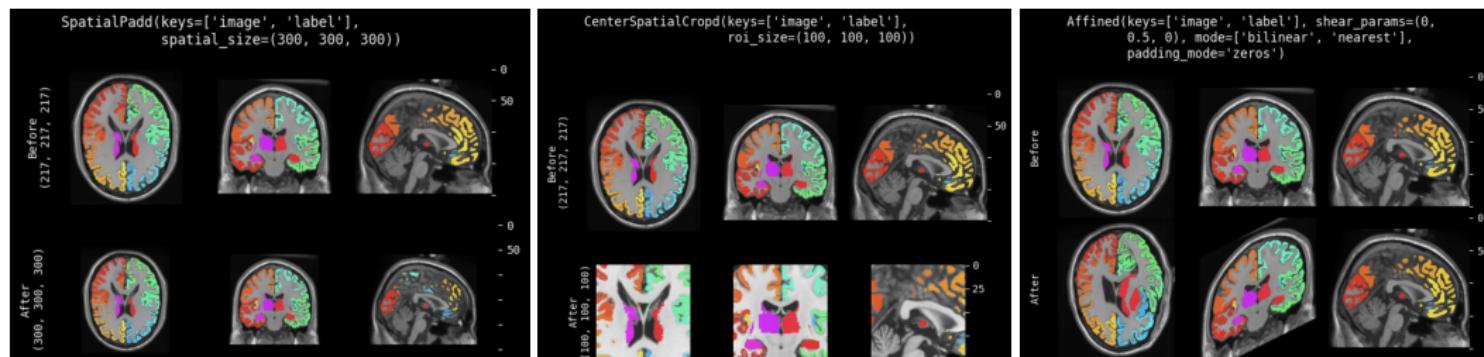


Figure: Examples of Monai Dictionary Transformations

Rotating 3D Images with Monai

- 1 Load image and label
- 2 Ensure Channel First
- 3 Use BorderPadd to ensure correct fill values for rotation
- 4 Affined rotation, padded with maximal spatial size for any rotation
- 5 Save image

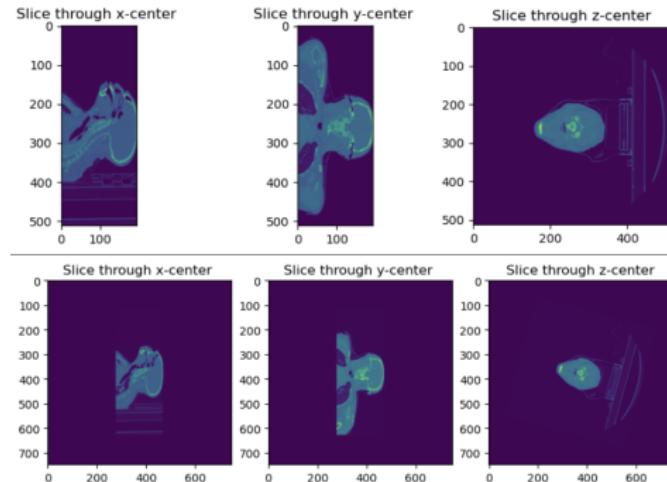


Figure: Example image before and after rotation with 15 degree rotation about z-axis

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Defining Robustness

"Robustness measures the resilience of a system towards perturbations in any of its components" [12]

- Local Robustness
 - For a given input x , model provides same result for x and all inputs x' within ball of radius δ centered at x
- Global Robustness
 - Model is locally robust for all inputs in the input space [13]
- Adversarial Robustness
 - Worst-case scenario, model's ability to resist being fooled
- Probabalistic/Physically Real Robustness
 - Probability that difference in δ close inputs satisfy Lipschitz property is greater than $(1 - \epsilon)$

$$\Pr_{x, x' \sim D} (||f(x') - f(x)|| \leq k * ||x' - x|| \mid ||x' - x|| \leq \delta) \geq 1 - \epsilon$$

- Still difficult to verify, but only have to show true with probability of at least $(1 - \epsilon)$ with respect to realistic input distribution

Proposed Inference Protocols

- Mean Absolute Error of Dice and sDice as robustness metric

$$DiceMAE(\epsilon) = \frac{\sum_{i=1}^n (|O_{Dice}^i - AR_{Dice}^i(\epsilon)^i|)}{n}$$

$$sDiceMAE(\epsilon) = \frac{\sum_{i=1}^n (|O_{sDice}^i - AR_{sDice}^i(\epsilon)|)}{n}$$

where n is number of patient samples, O_{Dice}^i is score of a given sample prior to rotation, AR^i is score of the given sample after rotation, and $\epsilon = [a \ b \ c]$ is the rotation array about (x, y, z)

- Plot with respect to increasing rotation around each axis
- Use Wilcoxon signed-rank tests (non-parametric alternative to t-test) to see if selected perturbations lead to significantly different Dice scores across samples as in [14].

Open Questions

- ➊ Should we focus on realistic cases for robustness test? Or take adversarial approach?
- ➋ Is there an exact criterion to answer "is this neural network robust"? Is this too problem dependent?
- ➌ If adversarial, should we stick with rotations across one axis at a time? Or try rotating across several dimensions at once since we have the capacity?

Questions?

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